



Concurs : Dabas- C.Lovrin

Loc lansare : Dabas- C.Lovrin

Latitudine : 47°12'7.340"N
Distanta : 159.239 km
Cod columbofil : 754543
Latitudine : 46° 5' 15.2' N

Longitudine : 19°18'1.310"E
Ora lansarii : 26.06.2026 06:13:00
Columbofil : Petrov Daniel
Longitudine : 20° 36' 24.1' E

Ceas Atomic : 25.06.2026 22:01:42 GPS Ceas Atomic : 27.06.2026 00:17:25 LIVE
Ceas Porumbel : 25.06.2026 22:01:42 +0 Ceas Porumbel : 27.06.2026 00:17:25 +0
Sincronizare : 25.06.2026 22:01:42 GPS +3h
Por. imbarcati : 22 Por. sositi : 22

Nr. crt	Serie inel	Col.	Nr. inel senzori	Sosire Data Ora	Nr. Sec	Nr. Ant	Nom	Observatii
001	RO 24 1076015F		DA005873	26.06 07:29:48.8	OK	01	006	
002	RO 25 0950966F		DA5C82A8	26.06 07:29:57.0	OK	01	010	
003	RO 25 0950927M		DA5C7FF4	26.06 07:30:48.5	OK	02	016	
004	RO 25 0950963F		DA5C8116	26.06 07:33:28.8	OK	02	002	
005	RO 25 0950976F		DA5C8095	26.06 07:34:10.7	OK	01	012	
006	RO 25 0950943M		DA5C810B	26.06 07:34:37.0	OK	01	021	
007	RO 25 0950903F		DA5C815A	26.06 07:35:13.3	OK	01	001	
008	RO 25 0950953F		DA5C836F	26.06 07:35:24.5	OK	02	013	
009	RO 25 2015133M		DA5C8028	26.06 07:36:15.8	OK	02	020	
010	RO 25 0950989F		DA5C8051	26.06 07:36:26.5	OK	02	007	
011	RO 25 0950974M		DA5C82C3	26.06 07:39:26.7	OK	02	022	
012	RO 25 2015139F		DA5C82DE	26.06 07:39:36.0	OK	02	005	
013	RO 25 0950987M		DA5C8109	26.06 07:41:04.4	OK	02	019	
014	RO 25 0950970F		DA5C8224	26.06 07:43:55.7	OK	01	014	
015	RO 25 2015134F		DA5C81A1	26.06 07:51:20.5	OK	01	011	
016	RO 25 0950909F		DA5C8123	26.06 07:56:42.7	OK	02	009	
017	RO 25 0950980M		DA0DE6D2	26.06 08:03:56.4	OK	02	017	
018	RO 25 0950920F		DA5C8251	26.06 08:18:38.3	OK	01	003	
019	RO 25 0950988F		DA5C81F1	26.06 08:29:07.1	OK	02	004	
020	RO 25 0950930M		DA5C80A4	26.06 08:32:52.2	OK	01	015	
021	RO 25 0950947M		DA5C801B	26.06 08:39:00.0	OK	02	018	
022	RO 25 0950951F		DA5C8040	26.06 09:12:14.7	OK	02	008	

Semnatura: Crescator Comisia control Comisia imbarcare

Versiune SW: RO -4.1

Cod concurs: 41474

Serie ceas: 231414

BENZING Live

Autorizare: AA9003EE

1: 38803045 2: 38204996