



Concurs : Virbita 2

Loc lansare : Virbita

Latitudine : 43°8'20.28"N

Distanța : 370.67 km

Cod columbofil : 749456

Latitudine : 44° 38" 46.6' N

Longitudine : 27°1'13.78"E

Ora lansării : 21.09.2025 08:06:00

Columbofil : DUNARINTU IONUT

Longitudine : 22° 53" 58.3' E

Ceas Atomic : 20.09.2025 14:23:32 GPS

Ceas Porumbel : 20.09.2025 14:23:32 +0

Sincronizare : 20.09.2025 14:23:32 GPS +3h

Por. imbarcati : 47

Ceas Atomic : 21.09.2025 17:42:54 LIVE

Ceas Porumbel : 21.09.2025 17:42:54 +0

Por. sositi : 22

Nr. crt	Serie inel	Col.	Nr. inel senzori	Sosire Data Ora	Nr. Sec	Nr. Ant	Nom	Observatii
001	RO 25 0539232F		DA4A5ACF	21.09 13:26:59.9	OK	01	021	
002	RO 25 0539226F		DA1F748D	21.09 13:38:00.9	OK	01	043	
003	RO 25 0539207F		DA4A5BC1	21.09 13:56:41.8	OK	01	013	
004	RO 25 1276765F		DA4A5E03	21.09 13:57:49.3	OK	01	011	
005	RO 25 0539235F		DA4A5B08	21.09 14:01:03.0	OK	01	044	
006	RO 25 0539250F		DA3A4965	21.09 14:01:10.1	OK	01	010	
007	RO 25 0539225F		DA4A5B30	21.09 14:02:15.0	OK	01	005	
008	RO 25 1276755F		DA4A5BE4	21.09 14:02:25.0	OK	02	017	
009	RO 25 1276752F		DA4A5AD5	21.09 14:06:41.8	OK	01	047	
010	RO 25 0539258F		DA4A5ABB	21.09 14:35:51.9	OK	01	009	
011	RO 25 0539210F		DA4A5AB3	21.09 14:36:24.6	OK	01	035	
012	RO 25 0539243F		DA1E5B5D	21.09 14:49:34.9	OK	01	027	
013	RO 25 0539255F		DA4A5AE3	21.09 14:50:37.4	OK	02	007	
014	RO 25 0539211F		DA4A5ADF	21.09 15:01:37.2	OK	02	012	
015	RO 25 0539233F		DA19F821	21.09 15:21:43.9	OK	02	014	
016	RO 25 0539251F		DA4A5B37	21.09 15:25:33.3	OK	02	022	
017	RO 25 0539206F		DA4A5C96	21.09 15:35:35.2	OK	01	025	
018	RO 25 0539217F		DA67FDC8	21.09 16:08:32.6	OK	02	029	
019	RO 25 0539238F		DA4A5C7E	21.09 16:25:33.3	OK	01	042	
020	RO 25 0539266F		DA4A5C5F	21.09 16:25:35.9	OK	01	016	
021	RO 25 0539240F		DA4262E1	21.09 16:59:59.6	OK	01	037	
022	RO 25 0539202F		DA4A5B6A	21.09 17:09:17.0	OK	01	002	

Semnatura: Crescator

Comisia control

Comisia imbarcare

Versiune SW: RO -4.40

Cod concurs: 15030

Serie ceas: 228093

BENZING Live

Autorizare: AA902457

1: 38804391 2: 42800000